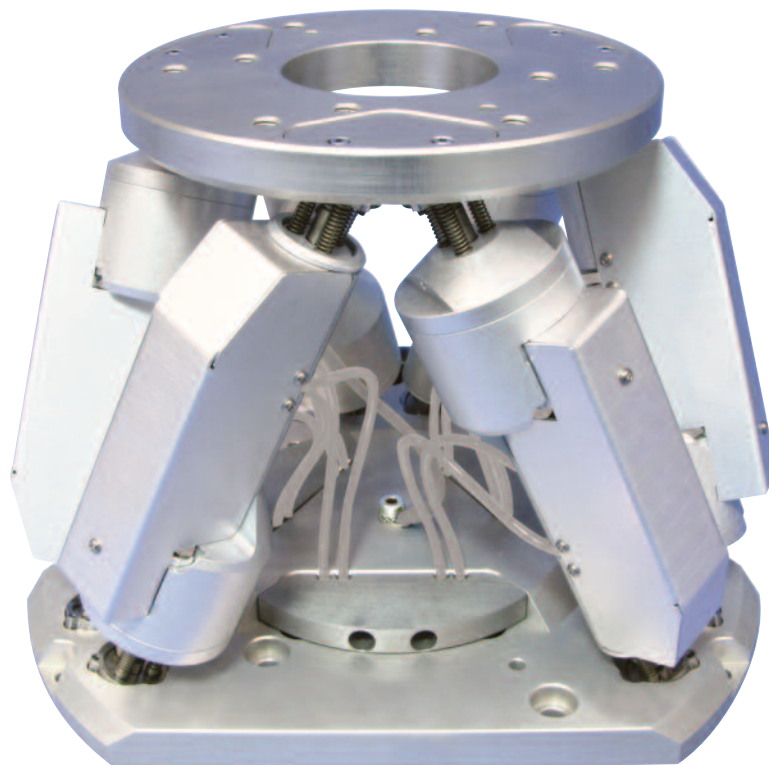




HXP50V6-MECA Hexapod

**Vacuum Compatible
6-Axis-Parallel Kinematic
Positioning System**



 **Newport®**

USER'S MANUAL

Warranty

Newport Corporation warrants this product to be free from defects in material and workmanship for a period of 1 year from the date of shipment. If found to be defective during the warranty period, the product will either be repaired or replaced at Newport's discretion.

To exercise this warranty, write or call your local Newport representative, or contact Newport headquarters in Irvine, California. You will be given prompt assistance and return instructions. Send the instrument, transportation prepaid, to the indicated service facility. Repairs will be made and the instrument returned, transportation prepaid. Repaired products are warranted for the balance of the original warranty period, or at least 90 days.

Limitation of Warranty

This warranty does not apply to defects resulting from modification or misuse of any product or part.

CAUTION



CAUTION

Please return equipment in the original (or equivalent) packing.

You will be responsible for damage incurred from inadequate packaging if the original packaging is not used.

Warranty does not apply to damages resulting from:

- **Incorrect usage:**
 - **Load on the Hexapod greater than maximum specified load.**
 - **Carriage speed higher than specified speed.**
 - **Improper grounding.**
 - **Connectors must be properly secured.**
 - **When the load on the Hexapod represents an electrical risk, it must be connected to ground.**
 - **Excessive or improper cantilever loads.**
- **Modification of the Hexapod or any part thereof.**

This warranty is in lieu of all other warranties, expressed or implied, including any implied warranty of merchantability or fitness for a particular use. Newport Corporation shall not be liable for any indirect, special, or consequential damages.

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Original instructions.

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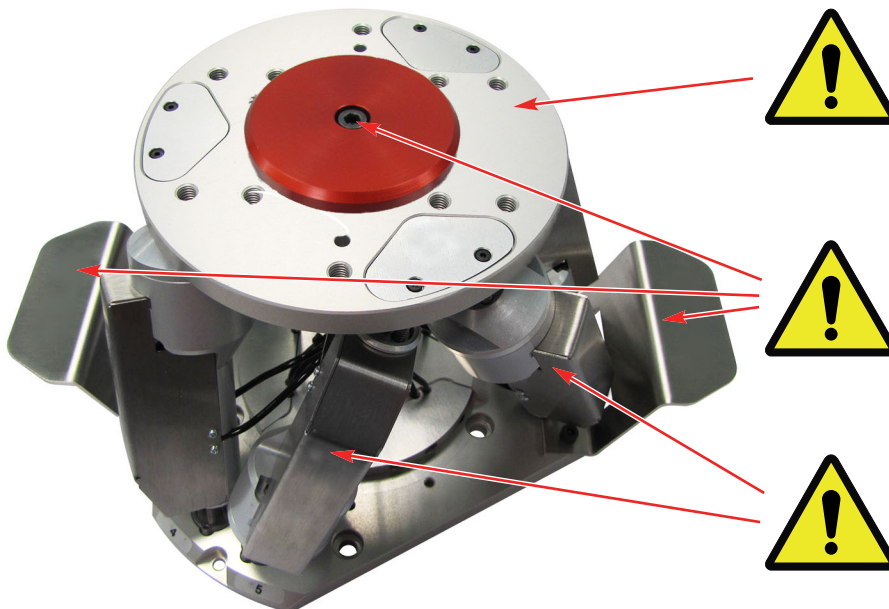
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Vacuum Compatible 6-Axis-Parallel Kinematic Positioning System

HXP50V6-MECA Hexapod

1.0 Introduction

This manual provides operating instructions for the Hexapod that you have purchased.



CAUTION

Do not use the top plate or struts for handling.

CAUTION

Remove lock and the 2 handles before use.

CAUTION

Do not manually turn struts.

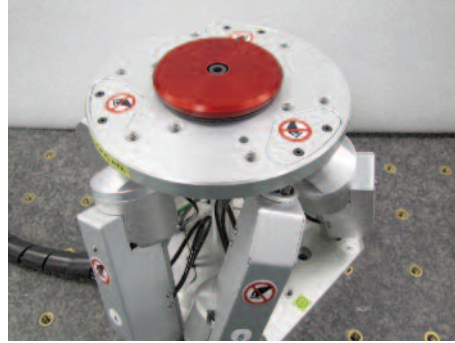


CAUTION

Please read all chapters of this manual carefully before operating your Hexapod.

1.1 Remove the Locking System

Hexapod ball studs can be damaged if they are subject to pulling. This can happen while handling or transportation of the HXP50V6-MECA.



To avoid damages, the HXP50V6-MECA is delivered with a locking system that includes a center rod and a clamping wheel.



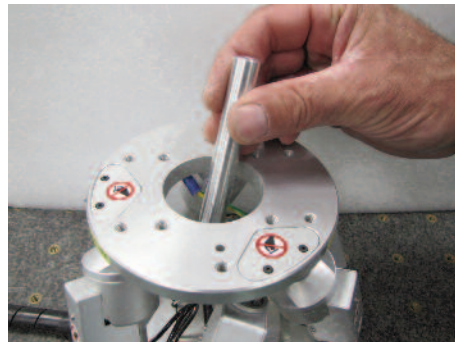
CAUTION

Remove the locking system before operating the HXP50V6-MECA Hexapod.

- 1 Remove the clamping wheel.



- 2 Remove the center rod.



NOTE

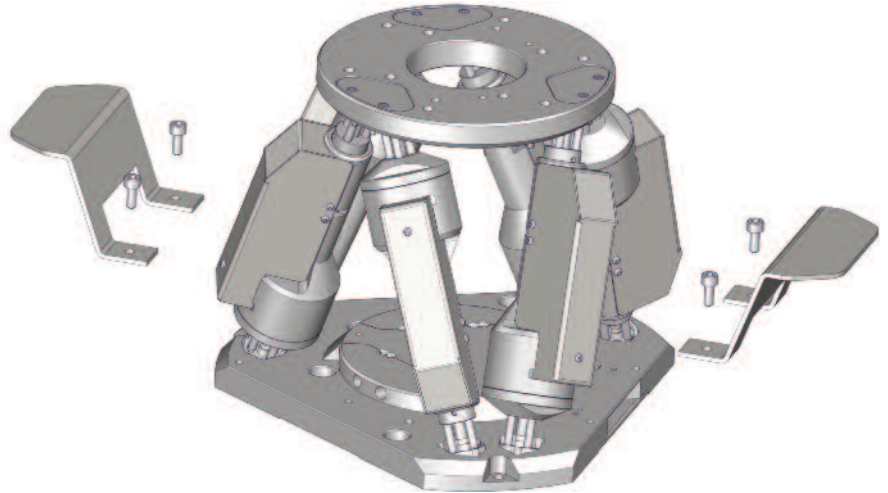
Pictures shown are for the standard HXP50-MECA, please use proper precautions when handling the vacuum compatible unit.

1.2 Removing the Shipping Handles

Unscrew the two M4 x 10 screws from each handle.

NOTE

Keep the handles and screws, as they will be needed everytime the HXP50V6-MECA is moved and carried.



CAUTION

Remove the 2 handles before using the HXP50V6-MECA Hexapod.

2.0 Description

The HXP50V6-MECA hexapod is a parallel kinematic motion device that provides six degrees of freedom: X, Y, Z, pitch, roll, and yaw. Hexapods are well known as effective solutions for complex motion applications that demand high load capacity and precision in up to six independent axes. Yet, they still have the image of being complex and highly priced. With the HXP50V6-MECA, Newport continues to introduce Hexapods that are not only affordable but also extremely easy to use.

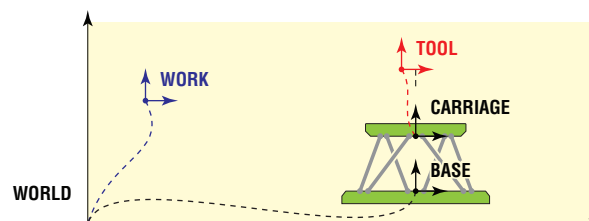
The HXP50V6-MECA is driven by six stepper motor driven actuators with encoder feedback, encoder on the motor, providing precise MIM, low backlash and fast speed. The HXP50V6-MECA can be run in open loop or closed loop, allowing the choice of different levels of performance like MIM and repeatability. The quality of the actuators has obviously a strong impact on the overall motion performance of the HXP50V6-MECA, but of equal importance are the joints with which the actuators are attached to the base and the moving top plate. With size and rigidity in mind, our engineers came up with innovative spherical joints that are not only very simple, but also enhance the stiffness of the hexapod.

The HXP50V6-ELEC-D controller accurately masters the synchronized transformations from Cartesian input coordinates to the motion of the Hexapod legs. In addition, the HXP50V6-ELEC-D provides advanced features including instrument grade I/O's, hardware based input triggers, event triggers, high-speed on-the-fly data acquisition, fast TCP/IP communication, and integrated TCL programming language for on-board processes. All these features improve accuracy and throughput, making the programmer's life much easier.

Two main advantages of the HXP50V6-MECA, as with the other Newport hexapods, are the ability to program two pivot points represented by the Tool and Work coordinate systems, and RightPath™ Trajectory Control. The Tool coordinate system moves with the top plate and the Work is stationary. Imagine a machine tool where one can adjust the orientation of both the cutting tool and workpiece or in photonics, the optical beam and the sample. Incremental displacements are possible in either system in user-friendly Cartesian coordinates, and positions can be easily switched from one system to the other by a function call or by numerical input in the HXP's web site interface. RightPath™ Trajectory Control enables scanning in a path along a defined trajectory, line, arc or rotation, with minimal runout and at a constant and definable speed enabling smooth well defined motion. These powerful functions are a completely new way of mastering Hexapod motions without the need for complex external coordinate transformations.



As a standard feature, the HXP50V6-ELEC-D controller allows the user to choose a virtual pivot point in space for all rotations.



Absolute moves and positions are defined in the work coordinate system. Incremental moves can be done in the tool or in the work coordinate systems.

3.0 Characteristics

3.1 Mechanical Specifications

	X	Y	Z	U (Rx)	V (Ry)	W (Rz)
Travel range ⁽¹⁾	±17 mm	±15 mm	±7 mm	±9°	±8.5°	±18°
MIM, Minimum incremental motion ⁽⁴⁾	0.2 μm/0.8 μm	0.2 μm/0.8 μm	0.1 μm/0.4 μm	0.1 mdeg/0.4 mdeg	0.1 mdeg/0.4 mdeg	0.2 mdeg/0.8 mdeg
Uni-directional repeatability, typical	±0.2 μm	±0.2 μm	±0.1 μm	±0.4 mdeg	±0.4 mdeg	±0.2 mdeg
Bi-directional repeatability, typical ⁽²⁾	±1 μm	±1 μm	±0.5 μm	±0.5 mdeg	±0.5 mdeg	±1 mdeg
Max. speed	2 mm/s	1.8 mm/s	0.8 mm/s	0.9 °/s	0.9 °/s	2 °/s
Stiffness ⁽³⁾	2 N/μm	2 N/μm	25 N/μm	–	–	–

¹⁾ Travel ranges are interdependent. The listed values are max. travels per axis when all other axis are in their centered position (Height = 151 mm for Z).

²⁾ With standard setting.

³⁾ Stiffness depends on Hexapod position. Values are given for all axis in their centered position.

⁴⁾ Open loop/Closed loop.

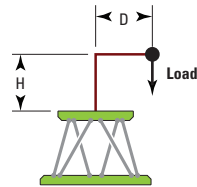


CAUTION

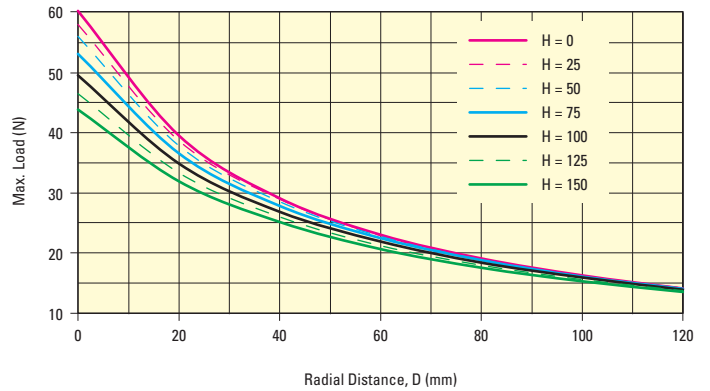
To reach specifications stated, stages must be fixed on a plane surface with a flatness of 50 μm or better.

3.2 Max. Cantilever Distance of the Load

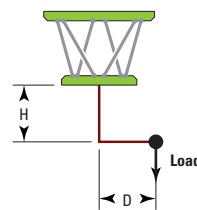
3.2.1 Horizontal Base Plate



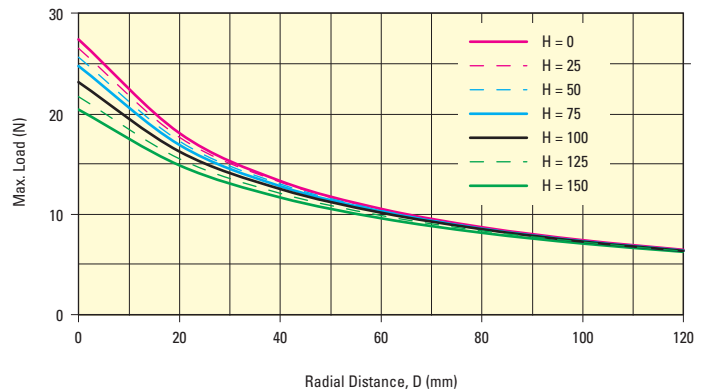
Load Position: D = 0 to 120 mm; H = 0 to 150 mm



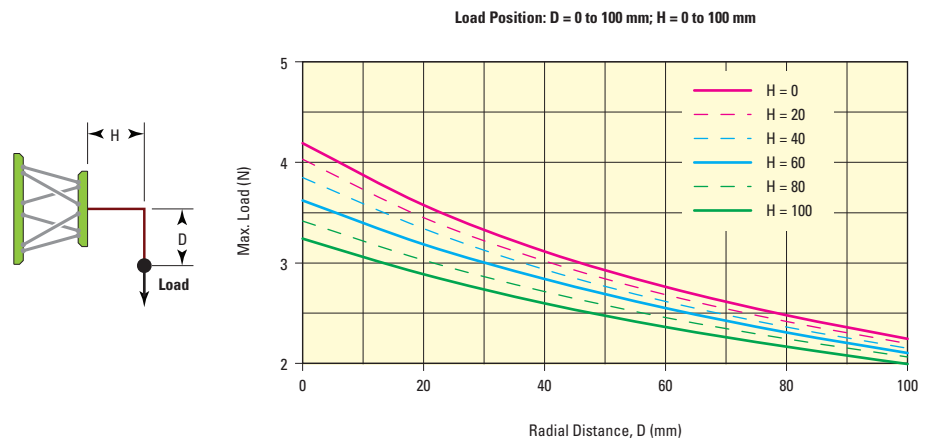
3.2.2 Base Plate Upside-Down



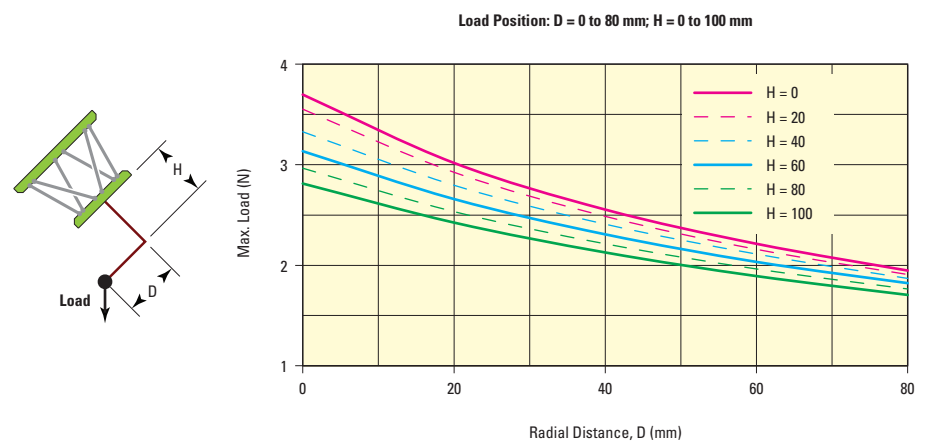
Load Position: D = 0 to 120 mm; H = 0 to 150 mm



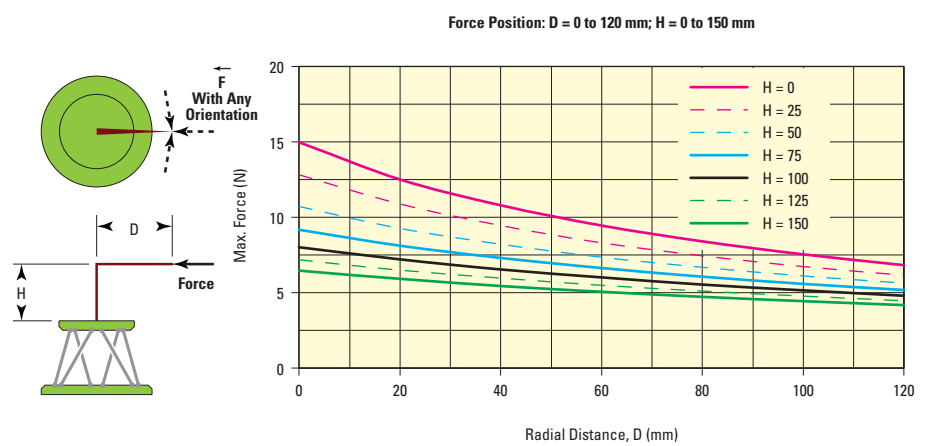
3.2.3 Vertical Base Plate



3.2.4 Base Plate at Any Position



3.2.5 Horizontal Base Plate - Lateral Force



3.3 Weight

	Weight [lb (kg)]
Hexapod (without cables)	4.7 (2.15)
Cables	2.8 (1.25)

4.0 Connection to the HXP50V6-ELEC-D Controllers

4.1 Warnings on Controllers

Controllers are intended for use by qualified personnel who recognize shock hazards and are familiar with safety precautions required to avoid possible injury. Read the controller user's manual carefully before operating the instrument and pay attention to all written warnings and cautions.

WARNING

Disconnect the power plug under the following circumstances:

- If the power cord or any attached cables are frayed or damaged in any way.
- If the power plug is damaged in any way.
- If the unit is exposed to rain, excessive moisture, or liquids are spilled on the unit.
- If the unit has been dropped or the case is damaged.
- If you suspect service or repair is required.
- Whenever you clean the electronics unit.

CAUTION

To protect the unit from damage, be sure to:

- Keep all air vents free of dirt and dust.
- Keep all liquids away from the unit.
- Do not expose the unit to excessive moisture (85% humidity).
- Read this manual before using the unit for the first time.



WARNING

All attachment plug receptacles in the vicinity of this unit are to be of the grounding type and properly polarized.

Contact your electrician to check your receptacles.

WARNING

This product is equipped with a 3-wire grounding type plug.

Any interruption of the grounding connection can create an electric shock hazard.

If you are unable to insert the plug into your wall plug receptacle, contact your electrician to perform the necessary alterations to ensure that the green (green-yellow) wire is attached to earth ground.

WARNING

This product operates with voltages that can be lethal.

Pushing objects of any kind into cabinet slots or holes, or spilling any liquid on the product, may touch hazardous voltage points or short out parts.

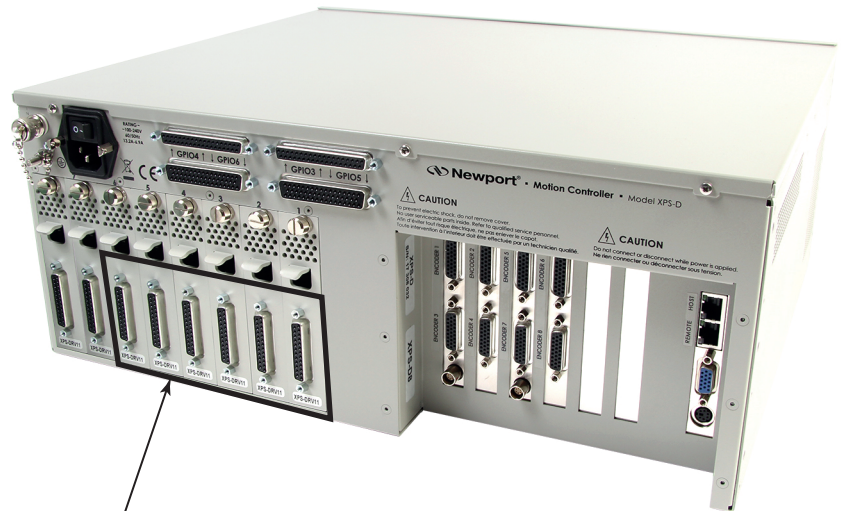
4.2 Connection



WARNING

Always turn the controller's power OFF before connecting to a strut.

Anytime prior to power-up, each strut must be connected with the supplied cable to the corresponding SUB-D25F plug located at the rear panel of the HXP50V6-ELEC-D controller, labeled "MOTOR".



6 SUB-D25F CONNECTORS FOR MOTOR CABLES

WARNING

Each Hexapod strut corresponds to the axis number of the HXP50V6-ELEC-D controller. This label is indicated on the SUB-D25M connector of the strut.



4.3 Cables

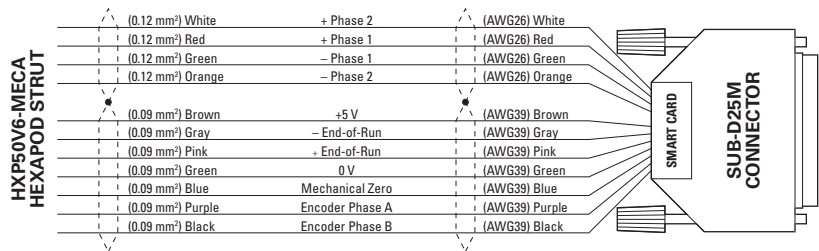
Each Hexapod is equipped with 1.5-meter cables (*) terminated with SUB-D25M connectors. These cables must be connected to the HXP50V6-ELEC-D. (*) Length from actuators. Remove 0.25m when measuring from hexapod output.

WARNING

The SUB-D25M connectors supplied with HXP50V6-MECA Hexapods are not vacuum compatible or intended for use in vacuum.

It is the customer’s responsibility to cut the cable and make connections to a vacuum feed trough following the instructions below:

- ❶ Cut the cable in half.
- ❷ Connect the flying leads of the cable half attached to HXP50V6-MECA strut to your feed through.
- ❸ Use the other half of the cable with SUB-D25M connector outside the vacuum to connect to HXP50V6-ELEC-D controller (the flying leads end of this cable to be connected to the feed through outside the vacuum chamber).
- ❹ Repeat steps 1-3 for all 6 axis /struts.
- ❺ Make sure to keep track of axis /strut numbers while modifying cables to avoid fatal errors or unexpected hexapod motions.



WARNING

These cables are shielded correctly. For a correct operation, make sure to lock connectors (ground continuity provided by the cable).

WARNING

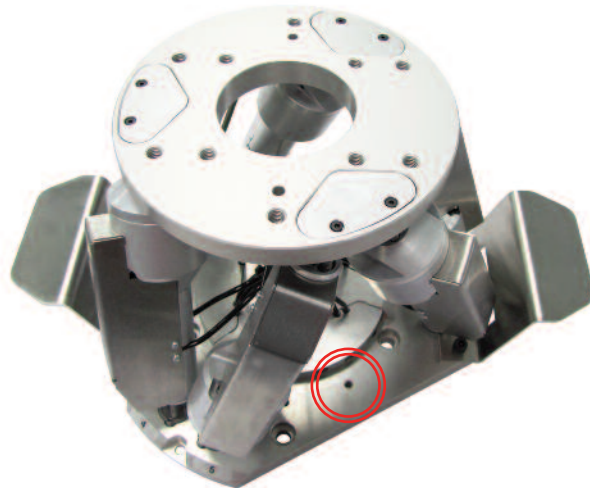
Keep the motor cables at a safe distance from other electrical cables in your environment to avoid potential cross talk.

NOTE

On each connector, a sticker indicates the home preset and backlash on the SUB-D25M connector.



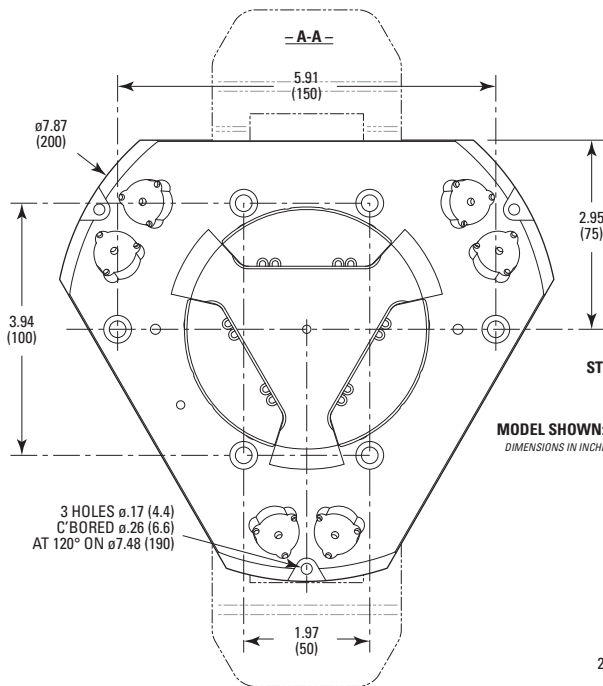
These parameters have to be set into the HXP50V6-ELEC-D controller for each strut. This is done at our factory when the HXP50V6-MECA Hexapod is ordered with the HXP50V6-ELEC-D controller.



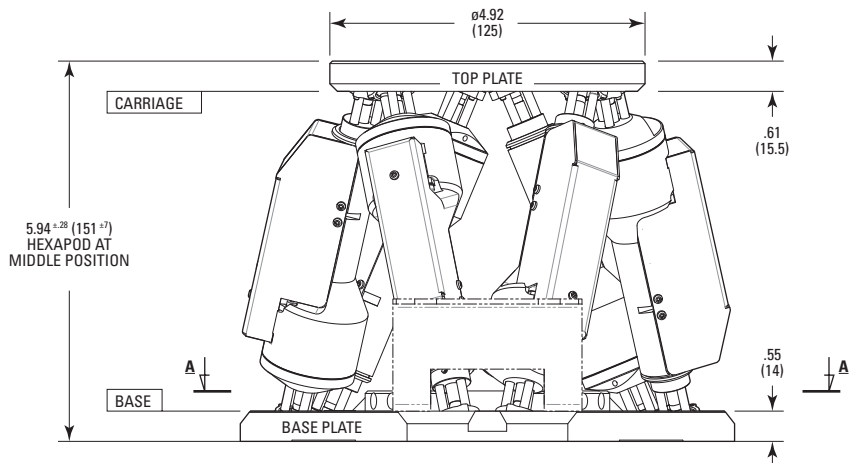
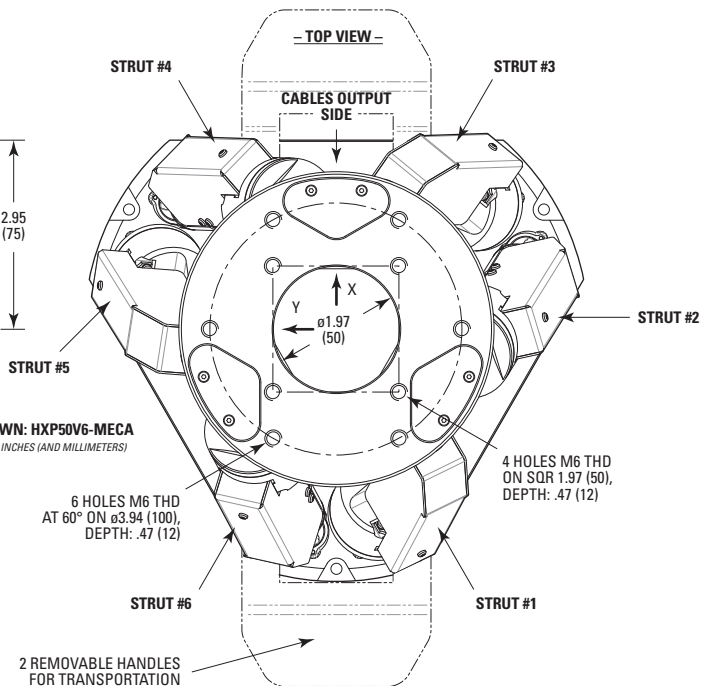
WARNING

The HXP50V6-MECA must be grounded via a threaded hole to avoid electrical disturbances generated by ground loops.

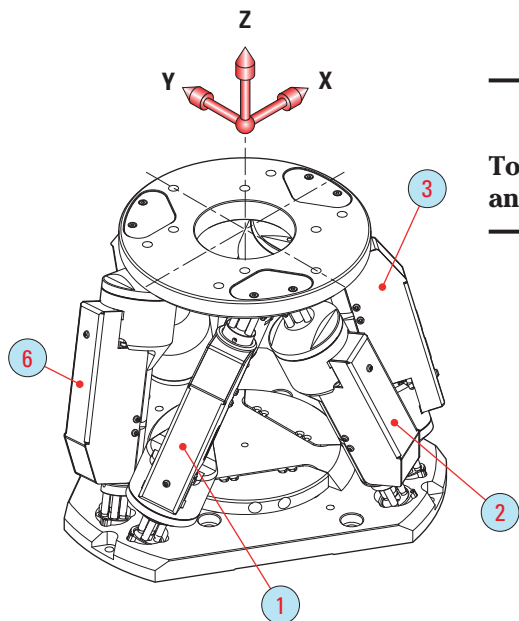
5.0 Dimensions



MODEL SHOWN: HXP50V6-MECA
DIMENSIONS IN INCHES (AND MILLIMETERS)



NOTE
The +X-axis points in the direction of the cable output between struts #3 and #4.



NOTE

Top and base plates of the HXP50V6-MECA Hexapod are made of anodized aluminum.

6.0 Maintenance

RECOMMENDATION

Please contact Technical Sales Support team for recommendations on application specific maintenance.

6.1 Maintenance

The Hexapod requires no particular maintenance. Nevertheless, this is a precision mechanical device that must be kept and operated with caution.

PRECAUTIONS

The Hexapod must be used or stocked in a clean environment, without dust, humidity, solvents or other substances.

RECOMMENDATION

It is recommended to return the Hexapod to Newport for re-lubrication after 2000 hours of use.

If the HXP50V6-MECA is mounted on a workstation and cannot be easily removed, please contact Newport's After Sales Service for further instructions.

Prior to removal, it is recommended to home the HXP50V6-MECA to its default home position (144 mm height). Install the original shipping handles prior to packing into the original packaging.

6.2 Repair

CAUTION



Never attempt to disassemble a component of the Hexapod that has not been covered in this manual.

To disassemble a non specified component can cause a malfunction of the stage.

If you observe a malfunction in your Hexapod, please contact us immediately to arrange for a repair.



CAUTION

Any attempt to disassemble or repair a Hexapod without prior authorization will void your warranty.



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