Hight Performance Long-Travel Motor Stages

IMS-LM-S Series



The IMS-LM-S series of linear motor stages are designed for self-supporting applications with travel ranges from 300 mm to 1200 mm. The stages feature a robust design with high performance at low cost, making them cost-effective solutions for precision industrial applications such as semiconductor wafer inspection, microelectronics test and assembly, pick and place, DNA sequencing, or laser machining. The IMS-LM-SA version with, 4-point mounting, is ideal for delay lines and other applications with non-flat mounting surfaces.

The IMS-LM-S series utilizes an FEM optimized extruded aluminum body that is extremely stiff and minimizes bending caused by different thermal expansion coefficients of the aluminum body and steel rails.

Unlike-screw driven stages, the IMS-LM-S employs a center-driven linear motor. This linear motor is absolutely noise-free and has the advantage of higher speed, acceleration and system responsiveness without wear on motor brushes or drive screws. Due to the fully integrated linear motor, the IMS-LM-S is more than 100 mm shorter in length than a comparable screw driven stage.

- Non-contact direct-drive system for high dynamic response & high reliability
- High-efficiency ironcore linear motor for rapid and repeatable positioning
- High resolution linear encoder for sub-μm repeatability & 20 nm MIM
- Stiff body design for rigid XY assemblies up to 600 x 600 mm travel
- Recirculating bearings with caged balls assure ultra-quiet motion

Thus, the IMS-LM-S is the optimum solution for space constrained applications that require high-throughput, high reliability, and ultra-quiet operation.

The IMS-LM-S uses a high efficiency 3-phase synchronous ironcore linear motor. While ironcore linear motors are often criticized for their cogging and high attractive forces, their efficiency is almost twice the efficiency of ironless linear motors. This results in higher acceleration capability and significantly less heat generation, which often limits performance of rapid point-to-point positioning.



Design Details

Base Material	Extruded Aluminum
Bearings	Recirculating bearings with caged balls
Drive System	3-phase synchronous ironcore linear motor (no Hall effect sensors)
Motor Initialization	Has to be done by the controller (without using Hall effect sensors)
Feedback	Linear steel scale, 20 µm signal period, 1 Vpp
Limit Switches	Optical
Home Switch	Optical, on encoder's fiducial track, located at center of travel
ESP Compatibility	Yes
Cable	A 5-m cable kit must be ordered separately
MTBF	A 5 20,000 hours

Recirculating ball bearing slides with caged balls provide excellent payload capacity and long life. The ball separators in the recirculating elements ensure superior smooth movement, lower noise, and longer service life compared to uncaged ball bearing slides.

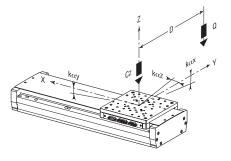
Precision position feedback is supplied by a highly repeatable linear scale mounted inside the stage. The

encoder signals are interpolated by Newport's motion controllers with outstanding 20 nm Minimum Incremental Motion, repeatability, and stability. Absolute home position and limit signals are incorporated to improve repeatability and reliability, while simplifying the design with less electronics and mechanical parts .

	Travel Range (mm)	IMS-LM-S	IMS-LM-SA-S
Travel Range (mm)		300, 400, 500, 600, 800, 1000 and 1200	800, 1000 and 1200
Minimum Incremental Motion (nm)		20	
Bidirectional Repeatability, Typical (Guaranteed) (1) (µm)	300 & 400-:	0-: ±0.08 (±0.25) –	
Typical (Guaranteed) (1) (µm)	500 & 600:	±0.09 (±0.25)	
	800:	±0.10 (± 0.50)0	±0.10 (± 0.50)
	1000:	±0.12 (± 0.50)	±0.12 (± 0.50)
	1200:	±0.13 (± 0.50)	±0.13 (± 0.50)
Accuracy, Typical (Guaranteed) (1) (μm)	300:	±1.7 (±4.5)	-
	400:	±2.0 (±4.5)	-
	500:	±2.5 (±5.5)	-
	600:	±3.0 (±7.5)	-
	800 & 1000:	±4.0 (±9.0)	±4.0 (±9.0)
	1200:	±5.0 (±9.0)	±5.0 (±15)
Maximum Speed (No Load) (2) (mm/s)		1000 (refer to chart below)	
Maximum Acceleration (No Load) (2) (m/s2)		40	
Moving mass (kg)		Carriage: 3.5 + Interface:1 = 4.5	
Drag force (torque)		Approx. 15 N	
Pitch, Typical (Guaranteed) (1) (3) (µrad)	300: to 500:	±37 (±75)	-
	600:	±50 (±125)	-
	800:	±100 (±200)	±100 (±200)
	1000:	±112 (±225)	±112 (±225)
	1200:	±125 (±250)	±125 (±250)
Yaw, Typical (Guaranteed) (1) (3) (µrad)	300:	±25 (±50)	-
	400 & 500:	±25 (±75)	-
	600:	±30 (±75)	-
	800 to 1200:	±40 (±150)	±40 (±150)

¹⁾ For the definition of Typical and Guaranteed specifications see "Motion Basics Terminology & Standards" Tutorial at www.newport.com

Load Characteristics and Stiffness



	IMS-LM-S	IMS-LM-SA-S
Cz, Normal center load capacity on bearings	600 N	100 N
kax, Angular stiffness (Roll)	1 μrad/Nm	2 μrad/Nm
kay, Angular stiffness (Pitch)	0.2 μrad/Nm	2 μrad/Nm
kaz, Angular stiffness (Yaw)	1 μrad/Nm	1 μrad/Nm
Q, Off-center load with D = Cantilever distance in mm	Q ≤ Cz/ (1 + D/90)	



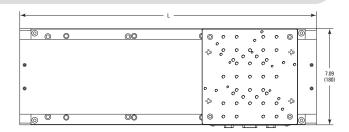
²⁾ Speed depends on the driver.

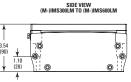
³⁾ To obtain arcsec units, divide μrad value by 4.8.



Dimensions

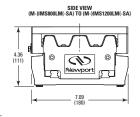






• (...) (....) (...) → .83 (21) .83 (21) → 5.91 (150) 5.91 (150) 5.91 (150) n1 x 2 HOLES CLR FOR M6 SCREW 5.91 (150) 6.0 (152.4) n2×2 HOLES CLR FOR 1/4-20 SCREW 5.0 (127) 5.0 (127) 5.0 (127)

(M-)IMS-LM(-SA)-S Stages



1.30 (33)

EL (METRIC)	n1	n2	TRAVEL	L
MS300LM-S	4	4	11.81 (300)	21.85 (555)
MS400LM-S	4	4	15.75 (400)	25.79 (655)
MS500LM-S	4	6	19.69 (500)	29.72 (755)
MS600LM-S	6	6	23.62 (600)	33.66 (855)
MS800LM-S	6	-	31.49 (800)	44.48 (1130)
MS1000LM-S	7	-	39.36 (1000)	52.35 (1330)
MS1200LM-S	8	-	47.23 (1200)	60.22 (1530)
MS800LM-SA-S	4 HOLES ON 2	6 × 6 (600 × 150)	31.49 (800)	44.48 (1130)
MS1000LM-SA-S	4 HOLES ON 2	8 × 6 (750 × 150)	39.36 (1000)	52.35 (1330)
MS1200LM-SA-S	4 HOLES ON 3	4×6 (900×150)	47.23 (1200)	60.22 (1530)

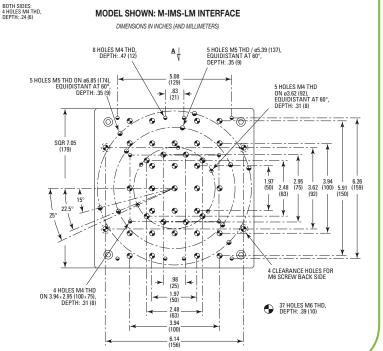
MODEL SHOWN: IMS300LM-S

DIMENSIONS IN INCHES (AND MILLIMETERS)



* 1.50 (38) * 5 HOLES M5 THD / ø5.39 (137), EQUIDISTANT AT 60°, DEPTH: .35 (9) 8 HOLES M4 THD, DEPTH: .47 (12) 5.08 (129) 5 HOLES M5 THD ON ø6.85 (174), EQUIDISTANT AT 60°, DEPTH: .35 (9) 5 HOLES M4 THD ON ø3.62 (92), EQUIDISTANT AT 60°, DEPTH: .31 (8) · 83 (21) SQR 7.05 (179) • 2.0 | 3.0 | 4.0 | 6.26 (50.8) 2.48 (76.2) 3.62 (101.6) 6.0 (159) | (63) | (92) | (152.4) | 4 CLEARANCE HOLES FOR M6 SCREW BACK SIDE 4 HOLES M4 THD ON 3.94×2.95 (100×75), DEPTH: .31 (8) 37 HOLES 1/4-20 THD, DEPTH: .39 (10) 2.48 .

6.14 (156)



MODEL SHOWN: M-IMS-LM INTERFACE



Dimensional Drawing

Recommended Controllers/Drivers

Model	Description
XPS-Dx	1- to 8-axis universal high-performance motion controller/driver
XPS-DRV11	Universal digital driver card for stepper, DC and direct motors
XPS-RL-Dx	1- to 4-axis universal high-performance motion controller/driver
XPS-EDBL	High-power, 3-phase, sinusoidal DC brushless motor driver
XPS-DRV00P	Pass-through driver module with pulse and direction capability

Cable Kits

Model	Description
XPS-DK22	Motorized stage cable kit, for stages IMS-LM-S, XML-S, XMS-S and XPS-DRV11 driver module
XPS-DK24	Motorized stage cable kit, for stages IMS-LM-S, XML-S, XMS-S and XPS-EDBL driver module

Ordering Information

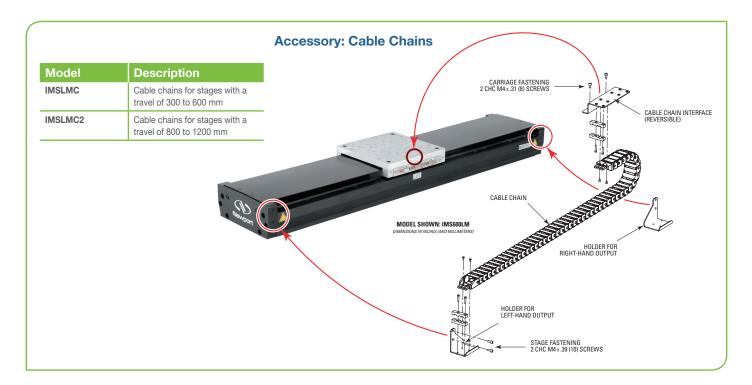
Model	Series	Travel (mm)	Drive	4-Point Mounting
		┌ 300 ┐		
		400		
		500		
M-	IMS -	600	LM -	— -SA ⁽¹⁾ — -S
		800		
		1000		
		_ 1200 _		

 $^{\scriptscriptstyle 1)}$ 800, 1000 and 1200 mm travels available.

M-: For metric version LM: Linear motor SA: 4-point mounting

Example:

The **M-IMS800LM-SA-S** is a metric version of IMS stage with 800 mm travel, a linear motor drive and 4-point mounting.





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