

Linear Metrology Stages

FMS SERIES



The FMS series all steel linear stages are engineered to address sensitive metrology applications that require stability, high straightness and flatness, such as surface measurements, profilometry, etc.

All Steel Body

The all steel construction allows for extreme stiffness and thermal stability, by eliminating bi-metallic bending. Due to the hardness of steel, it can be machined flatter to give excellent trajectory.

Anti-creep Crossed Roller Bearings

To ensure the most accurate trajectory control, FMS stages feature matched pairs of best-in-class anti-creep crossed roller bearings. The absence of recirculating elements in these bearings leads to outstanding ripple-free motion adequate for the most demanding scanning and inspection systems. Moreover, the geared retainers prevent bearing cage migration, which can occur with other linear bearing products.

Plug and Play - ESP Compatible

The FMS is an ESP-compatible stage. When connected to a Newport controller, it is quickly recognized and configured without the need for user input, facilitating the startup and usability of the FMS.

This Plug and Play feature is not only transparent to the use, but it also ensures the safe operation of the stage.

Precision Ground Ball Screw

The ground ball screw ensures higher speed motion and enables higher throughput capability over the long life of the FMS.

Metrology Report Included at No Additional Cost

Newport guarantees specification values which are measured and recorded following ASME B5.57 and ISO 230-2 standards. The typical performance values are two times better than the guaranteed specifications.

- Engineered to address demanding surface measurement and profilometry applications
- All steel construction for high stiffness, thermal stability, repeatable positioning and overall durability
- Anti-creep crossed roller bearings to provide exceptional straightness and flatness while reducing measurement noise and eliminating measurement variability
- High accuracy and repeatability enabled by linear encoder and precision ball screw
- Plug and Play - ESP compatible
- 100 to 300 mm travel range

SPECIFICATIONS

| | FMC-CC | FMC-PP | FMC-PPHA |
|--|---------------------------|---------------------------|---------------------------|
| Travel Range (mm) | | 100; 200; 300 | |
| Minimum Incremental Motion (μm) | 0.5 | 0.1 ⁽¹⁾ | 0.1 |
| Uni-directional Repeatability, Typical (Guaranteed) (μm) | ± 0.40 (± 0.75) | ± 0.35 (± 0.75) | ± 0.06 (± 0.10) |
| Bi-directional Repeatability ⁽²⁾ , Typical (Guaranteed) (μm) | ± 0.8 (± 1.5) | ± 1.3 (± 2.25) | ± 0.15 (± 0.25) |
| Maximum Speed (mm/s) | 100 | 20 | 50 |

| | FMS100 | FMS200 | FMS300 |
|--|---------------------------|-------------------------|-------------------------|
| Accuracy ⁽²⁾ , -CC and -PP | ± 1.5 (± 3.0) | ± 2.0 (± 5.0) | ± 2.5 (± 6.5) |
| Typical (Guaranteed) (μm), -PPHA | ± 0.2 (± 0.5) | ± 0.4 (± 1.0) | ± 0.5 (± 1.5) |
| Straightness, Flatness ⁽²⁾ , Typical (Guaranteed) (μm) | ± 0.25 (± 0.75) | ± 0.5 (± 1.5) | ± 1.0 (± 3.0) |
| Pitch ⁽²⁾⁽³⁾ , Typical (Guaranteed) (μrad) | ± 15 (± 40) | ± 20 (± 50) | ± 30 (± 60) |
| Yaw ⁽²⁾⁽³⁾ , Typical (Guaranteed) (μrad) | ± 4.0 (± 10) | ± 5.0 (± 15) | ± 6.0 (± 20) |

¹⁾ 0.1 μm with XPS; 0.5 μm with SMC100PP and ESP301.

²⁾ For the definition of Typical and Guaranteed specifications see "Motion Basics Terminology & Standards" Tutorial at www.newport.com

³⁾ To obtain arcsec units, divide μrad value by 4.8.

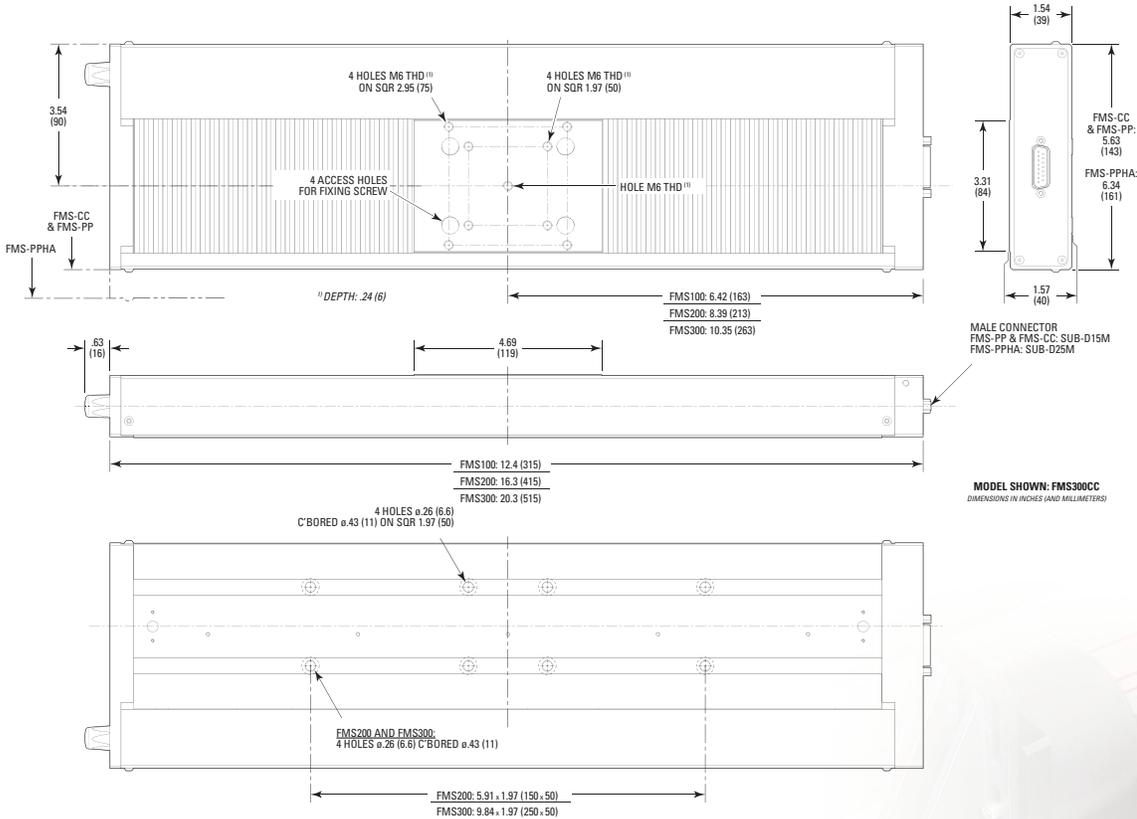
DESIGN DETAILS

| | |
|------------------------|--|
| Base Material | Stainless Steel |
| Bearings | Crossed Roller Bearings |
| Drive Mechanism | 8 mm, precision ground ball screw |
| Drive Screw Pitch (mm) | 2 |
| Feedback | DC: Screw mounted rotary encoder, 4000 cts/rev, index pulse PP: No feedback PPHA: Steel scale, 50 nm |
| Origin | PP: optical, located ~9.5 mm from negative software limit CC & PPHA: Optical, located ~10.5 mm from negative software limit |
| Drive Type | Stepper and DC Servo |
| Cable (m) | 3 (included) |

RECOMMENDED CONTROLLERS/DRIVERS

| Model | Description |
|------------------|--|
| XPS-D | 1- to 8-axis universal high-performance motion controller/driver |
| XPS-DRV11 | Universal digital driver card for stepper, DC and direct motors |
| XPS-RL | 1- to 4-axis universal high-performance motion controller/driver |
| XPS-DRV01 | PWM drive module for DC brush and stepper motors, 3 A/43 V max. |
| ESP301 | 1- to 3-axis motion controller/driver |
| SMC100CC | Single-axis DC motor controller/driver |
| SMC100PP | Single-axis stepper motor controller/driver |

DIMENSIONS



ORDERING INFORMATION

| Model | Description |
|-------------------|---|
| FMS100CC | Metrology Linear Stage, 100 mm Travel, DC Motor |
| FMS100PP | Metrology Linear Stage, 100 mm Travel, Stepper Motor |
| FMS100PPHA | Metrology Linear Stage, High Accuracy, 100 mm Travel, Stepper Motor |
| FMS200CC | Metrology Linear Stage, 200 mm Travel, DC Motor |
| FMS200PP | Metrology Linear Stage, 200 mm Travel, Stepper Motor |
| FMS200PPHA | Metrology Linear Stage, High Accuracy, 200 mm Travel, Stepper Motor |
| FMS300CC | Metrology Linear Stage, 300 mm Travel, DC Motor |
| FMS300PP | Metrology Linear Stage, 300 mm Travel, Stepper Motor |
| FMS300PPHA | Metrology Linear Stage, High Accuracy, 300 mm Travel, Stepper Motor |

LOAD CHARACTERISTICS AND STIFFNESS

| | | |
|--------------|-------------------------------|------------------------------|
| C_z | Normal centered load capacity | 150 N |
| $-C_x, +C_x$ | Axial load capacity | <30 N |
| K_{ax} | Compliance in roll | 3.0 μ rad/Nm |
| K_{ay} | Compliance in pitch | 2.0 μ rad/Nm |
| K_{az} | Compliance in yaw | 2.0 μ rad/Nm |
| Q | Off-center load (N) | $Q \leq C_z \div (1 + D/80)$ |

Where D = Cantilever distance (mm)

